

Data Mining

Lecture Notes for Chapter 4

Artificial Neural Networks

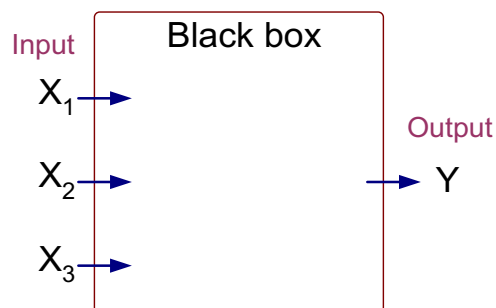
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by

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Artificial Neural Networks (ANN)

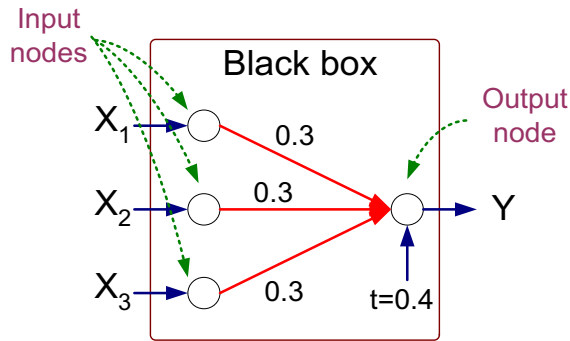
X_1	X_2	X_3	Y
1	0	0	-1
1	0	1	1
1	1	0	1
1	1	1	1
0	0	1	-1
0	1	0	-1
0	1	1	1
0	0	0	-1



Output Y is 1 if at least two of the three inputs are equal to 1.

Artificial Neural Networks (ANN)

X_1	X_2	X_3	Y
1	0	0	-1
1	0	1	1
1	1	0	1
1	1	1	1
0	0	1	-1
0	1	0	-1
0	1	1	1
0	0	0	-1

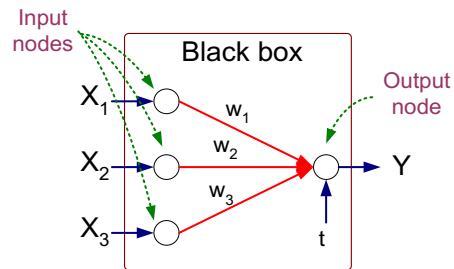


$$Y = \text{sign}(0.3X_1 + 0.3X_2 + 0.3X_3 - 0.4)$$

$$\text{where } \text{sign}(x) = \begin{cases} 1 & \text{if } x \geq 0 \\ -1 & \text{if } x < 0 \end{cases}$$

Artificial Neural Networks (ANN)

- Model is an assembly of inter-connected nodes and weighted links
- Output node sums up each of its input value according to the weights of its links
- Compare output node against some threshold t

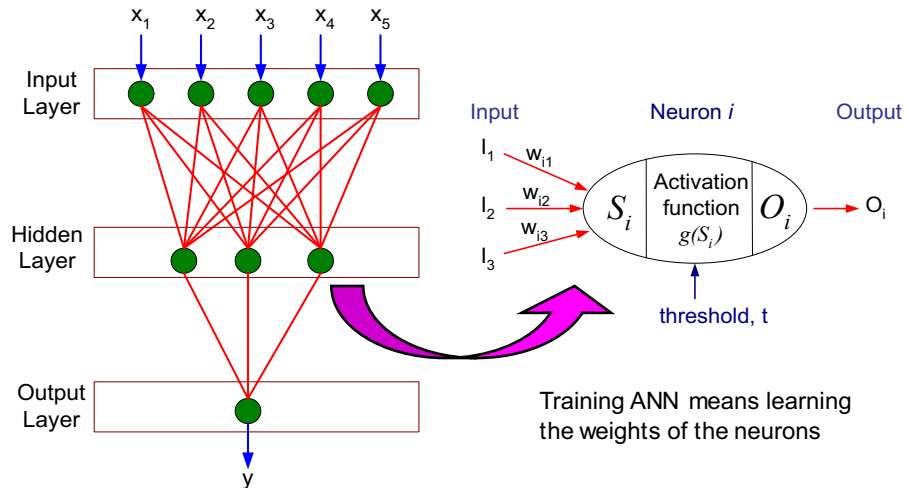


Perceptron Model

$$Y = \text{sign}\left(\sum_{i=1}^d w_i X_i - t\right)$$

$$= \text{sign}\left(\sum_{i=0}^d w_i X_i\right)$$

General Structure of ANN



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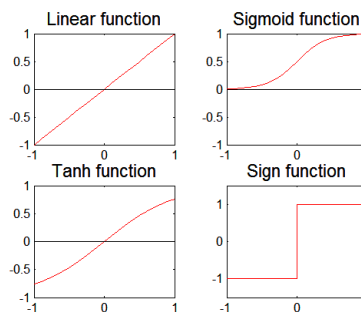
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Artificial Neural Networks (ANN)

- Various types of neural network topology
 - single-layered network (perceptron) versus multi-layered network
 - Feed-forward versus recurrent network

- Various types of activation functions (f)

$$Y = f\left(\sum_i w_i X_i\right)$$



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Perceptron

- Single layer network
 - Contains only input and output nodes
- Activation function: $f = \text{sign}(w \cdot x)$
- Applying model is straightforward

$$Y = \text{sign}(0.3X_1 + 0.3X_2 + 0.3X_3 - 0.4)$$

$$\text{where } \text{sign}(x) = \begin{cases} 1 & \text{if } x \geq 0 \\ -1 & \text{if } x < 0 \end{cases}$$

- $X_1 = 1, X_2 = 0, X_3 = 1 \Rightarrow y = \text{sign}(0.2) = 1$

Perceptron Learning Rule

- Initialize the weights (w_0, w_1, \dots, w_d)
- Repeat
 - For each training example (x_i, y_i)

- ◆ Compute $f(w, x_i)$
- ◆ Update the weights:

$$w^{(k+1)} = w^{(k)} + \lambda [y_i - f(w^{(k)}, x_i)] x_i$$

- Until stopping condition is met

Perceptron Learning Rule

- Weight update formula:

$$w^{(k+1)} = w^{(k)} + \lambda [y_i - f(w^{(k)}, x_i)] x_i ; \lambda : \text{learning rate}$$

- Intuition:

- Update weight based on error: $e = [y_i - f(w^{(k)}, x_i)]$
- If $y=f(x,w)$, $e=0$: no update needed
- If $y>f(x,w)$, $e=2$: weight must be increased so that $f(x,w)$ will increase
- If $y<f(x,w)$, $e=-2$: weight must be decreased so that $f(x,w)$ will decrease

Example of Perceptron Learning

$$w^{(k+1)} = w^{(k)} + \lambda [y_i - f(w^{(k)}, x_i)] x_i$$

$$Y = \text{sign}\left(\sum_{i=0}^d w_i X_i\right)$$

$$\lambda = 0.1$$

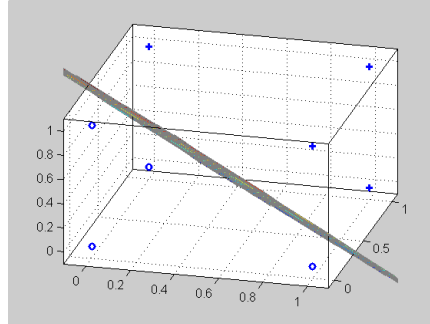
X_1	X_2	X_3	Y
1	0	0	-1
1	0	1	1
1	1	0	1
1	1	1	1
0	0	1	-1
0	1	0	-1
0	1	1	1
0	0	0	-1

	w_0	w_1	w_2	w_3
0	0	0	0	0
1	-0.2	-0.2	0	0
2	0	0	0	0.2
3	0	0	0	0.2
4	0	0	0	0.2
5	-0.2	0	0	0
6	-0.2	0	0	0
7	0	0	0.2	0.2
8	-0.2	0	0.2	0.2

Epoch	w_0	w_1	w_2	w_3
0	0	0	0	0
1	-0.2	0	0.2	0.2
2	-0.2	0	0.4	0.2
3	-0.4	0	0.4	0.2
4	-0.4	0.2	0.4	0.4
5	-0.6	0.2	0.4	0.2
6	-0.6	0.4	0.4	0.2

Perceptron Learning Rule

- Since $f(w,x)$ is a linear combination of input variables, decision boundary is linear

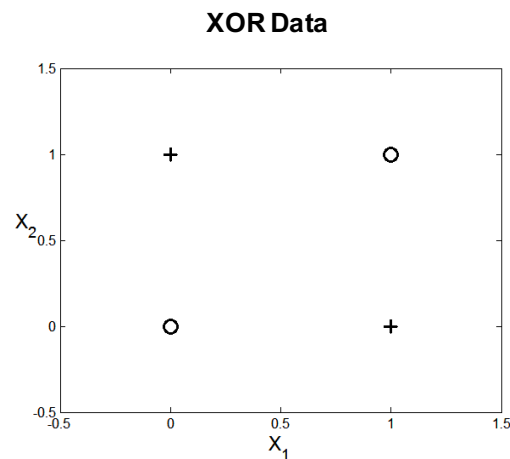


- For nonlinearly separable problems, perceptron learning algorithm will fail because no linear hyperplane can separate the data perfectly

Nonlinearly Separable Data

$$y = x_1 \oplus x_2$$

x_1	x_2	y
0	0	-1
1	0	1
0	1	1
1	1	-1



Multilayer Neural Network

- Hidden layers
 - intermediary layers between input & output layers
- More general activation functions (sigmoid, linear, etc)

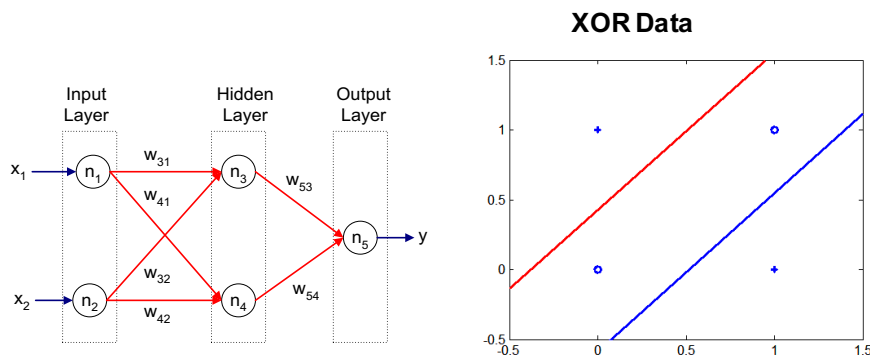
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Multi-layer Neural Network

- Multi-layer neural network can solve any type of classification task involving nonlinear decision surfaces



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Learning Multi-layer Neural Network

- Can we apply perceptron learning rule to each node, including hidden nodes?
 - Perceptron learning rule computes error term $e = y - f(w, x)$ and updates weights accordingly
 - ◆ Problem: how to determine the true value of y for hidden nodes?
 - Approximate error in hidden nodes by error in the output nodes
 - ◆ Problem:
 - Not clear how adjustment in the hidden nodes affect overall error
 - No guarantee of convergence to optimal solution

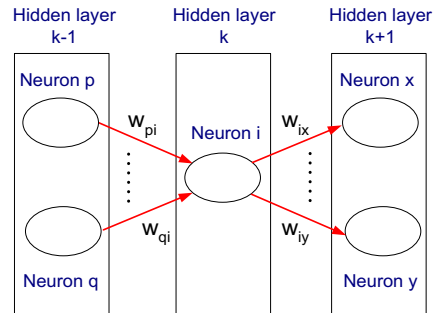
Gradient Descent for Multilayer NN

- Weight update: $w_j^{(k+1)} = w_j^{(k)} - \lambda \frac{\partial E}{\partial w_j}$
- Error function: $E = \frac{1}{2} \sum_{i=1}^N \left(t_i - f\left(\sum_j w_j x_{ij}\right) \right)^2$
- Activation function f must be differentiable
- For sigmoid function:
$$w_j^{(k+1)} = w_j^{(k)} + \lambda \sum_i (t_i - o_i) o_i (1 - o_i) x_{ij}$$
- Stochastic gradient descent (update the weight immediately)

Gradient Descent for MultiLayer NN

- For output neurons, weight update formula is the same as before (gradient descent for perceptron)

- For hidden neurons:



$$w_{pi}^{(k+1)} = w_{pi}^{(k)} + \lambda o_i (1 - o_i) \sum_{j \in \Phi_i} \delta_j w_{ij} x_{pj}$$

$$\text{Output neurons : } \delta_j = o_j (1 - o_j) (t_j - o_j)$$

$$\text{Hidden neurons : } \delta_j = o_j (1 - o_j) \sum_{k \in \Phi_j} \delta_k w_{jk}$$

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Design Issues in ANN

- Number of nodes in input layer
 - One input node per binary/continuous attribute
 - k or $\log_2 k$ nodes for each categorical attribute with k values
- Number of nodes in output layer
 - One output for binary class problem
 - k or $\log_2 k$ nodes for k-class problem
- Number of nodes in hidden layer
- Initial weights and biases

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Characteristics of ANN

- Multilayer ANN are universal approximators but could suffer from overfitting if the network is too large
- Gradient descent may converge to local minimum
- Model building can be very time consuming, but testing can be very fast
- Can handle redundant attributes because weights are automatically learnt
- Sensitive to noise in training data
- Difficult to handle missing attributes

Recent Noteworthy Developments in ANN

- Use in deep learning and unsupervised feature learning
 - Seek to automatically learn a good representation of the input from unlabeled data
- Google Brain project
 - Learned the concept of a 'cat' by looking at unlabeled pictures from YouTube
 - One billion connection network